SDC11558

#### **General Description**

The SDC11558 is a single phase full wave motor driver for DC fan motors, and can apply to three type speed control methods. The output signals of this IC are the amplifications of hall input signals. It is suitable for both game machine and CPU cooler that need silent fans. The device is built-in lock protection. When the fan is locked, the device will enter the lockup protection mode. It is also with thermal shutdown function. In normal operation, the supply current is less than 5mA. The SDC11558 is available in MSOP-10 package.

#### **Pin Configuration**



MSOP-10

#### **Features**

- Silent driver
- Three speed control methods
- Built-in lock protection and auto restart function
- Low standby current (PWM=0), supply current less than 200uA (Type C only)
- Adjustable fan speed slope (Type B only)
- FG output
- Include hall bias circuit
- Built-in thermal protection circuit(RoHS compliant)
- Low duty start up

#### **Applications**

Motor drivers for silent fan motors

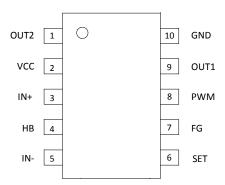


Figure 1. Pin Configuration

Pin Number	Pin Name	Function
1	OUT2	Motor output terminal 2
2	VCC	Power supply terminal
3	IN+	Hall input terminal+
4	НВ	Hall bias terminal
5	IN-	Hall input terminal-
6	SET	Speed slope setting terminal.
7	FG	FG signal output terminal
8	PWM	PWM signal input terminal
9	OUT1	Motor output terminal 1
10	GND	GND terminal

Table 1. Pin Description

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#### **Functional Block Diagram**

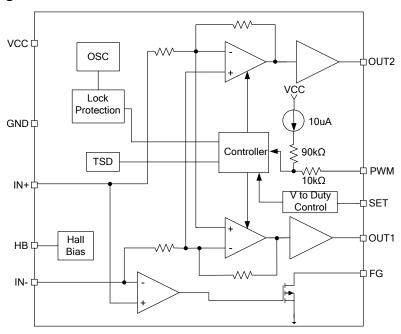
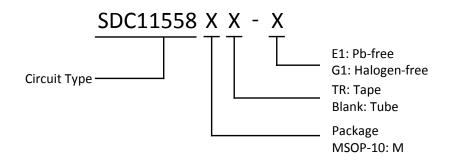


Figure 2. Functional Block Diagram

## **Ordering Information**



Package	Temperature Range	Part N	Mar	Packing		
		Pb-free	Halogen-free	Pb-free	Halogen-free	Туре
MSOP-10	-40°C~85°C	SDC11558MTR-E1	SDC11558MTR-G1	11558	11558G	Таре
		SDC11558M-E1	SDC11558M-G1	11558	11558G	Tube



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**Absolute Maximum Ratings** (Note: Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device.)

Parameter	Symbol	Conditions	Min	Max	Unit
VCC pin supply voltage	$V_{cc}$	-	-0.3	8.0	V
Output pin maximum output current	I <sub>out</sub>	-	-	1.0	Α
Output pin output voltage	V <sub>OUT</sub>	-	-0.3	8.0	V
HB pin maximum output current	I <sub>HB</sub>	-	-	10.0	mA
FG pin output voltage	$V_{FG}$	-	-0.3	8.0	V
FG pin maximum output sink current	I <sub>FG</sub>	-	-	10.0	mA
VH/VL pin supply voltage	$V_{SET}$		-0.3	8.0	V
Storage temperature range	$T_{STG}$	-	-65	150	°C
Maximum lead soldering temperature, 10 seconds	T <sub>SDR</sub>	-	-	260	°C
Maximum junction temperature range	TJ	-	-40	150	°C

Table 2. Absolute Maximum Ratings

## **Recommended Operating Conditions**

Parameter	Symbol	Conditions	Min	Max	Unit
VCC pin supply voltage range	V <sub>cc</sub>	-	2.0	6.0	V
Hall input voltage range	$V_{HALL}$	-	0.4	V <sub>cc</sub> -1.1	V
SET pin input voltage range	$V_{SET}$	-	0.1	$V_{HB}$	٧
Ambient temperature	Та	-	-40	105	°C

Table 3. Recommended Operating Conditions

## **Electrical Characteristics** (Ta=25°C, V<sub>CC</sub>=5V, unless otherwise specified)

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
HB pin output voltage	V <sub>HB</sub>	I <sub>HB</sub> =-5mA	1.1	1.3	1.5	V
Operating current	I <sub>CC1</sub>	Rotation mode and lock protection mode		4	5	mA
	I <sub>CC2</sub>	Standby mode (PWM=0)	-	0.1	0.2	μΑ
Lock detection on time	t <sub>on</sub>	-	0.35	0.5	0.65	S
Lock detection off time	t <sub>OFF</sub>	-	3.5	5	6.5	S
Output driver saturation voltage	Vo	I <sub>OUT</sub> = 250mA, Upper and lower total	-	0.3	0.44	V
FG pin low voltage	$V_{FG}$	I <sub>FG</sub> = 5mA	-	0.2	0.4	V
FG pin leakage current	I <sub>FGL</sub>	V <sub>FG</sub> = 5V	-	<0.1	1	μΑ
Input - output gain	GIO	V <sub>OUT</sub> /(VIN+~VIN-)	44	45	46	dB
SET pin high level input leakage	I <sub>SETH</sub>	$V_{SET} = V_{CC}$	-	-	0.1	μΑ
SET pin low level output current	I <sub>SETL</sub>	V <sub>SET</sub> = 0V	-	1	-	μΑ
PWM input high level voltage	V <sub>PWMH</sub>	-	0.5xV <sub>cc</sub>	-	V <sub>cc</sub> +0.5	V

January, 2013 Rev. 1.0

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# **Electrical Characteristics** (Ta=25°C, V<sub>CC</sub>=5V, unless otherwise specified)

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
PWM input low level voltage	$V_{PWML}$	-	0	-	0.2xV <sub>cc</sub>	V
PWM input frequency	$f_{PWM}$	-	0.02	-	50	kHz
Quick start enable time	t <sub>QS</sub>	-	-	66.5	90	ms
Hall input offset voltage	$V_{HOFS}$	-	-	-	±6	mV
Input hysteresis voltage	$V_{HYS}$	-	±5	±10	±15	mV
Over temperature shutdown threshold	OTS	-	-	165	-	°C
Over temperature shutdown hysteresis	-	-	-	30	-	°C

Table 4. Electrical Characteristics

#### **Truth Table**

Input			Output			Mode	
IN-	IN+	PWM	OUT1	OUT2	FG	iviode	
L	Н		Н	L	L		
Н	L	Н	L	Н	OFF	Newsol are arctical and a	
Н	L		L	L	OFF	Normal operation mode	
L	Н	L	L	L	L		
L	Н		L	L	OFF	La de mante etimo mende	
Н	L	-	L	L	OFF	Lock protection mode	
-	-	L	OFF	OFF	OFF	Standby mode	

Table 5. Truth Table

## **Power Dissipation Curve**

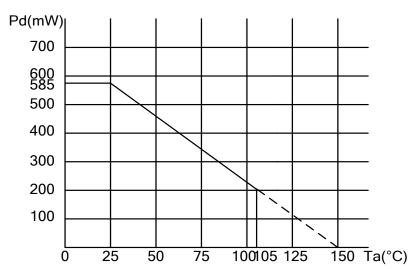


Figure 2. Power Dissipation Curve

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# **Typical Application**

# Type A: VCC speed control

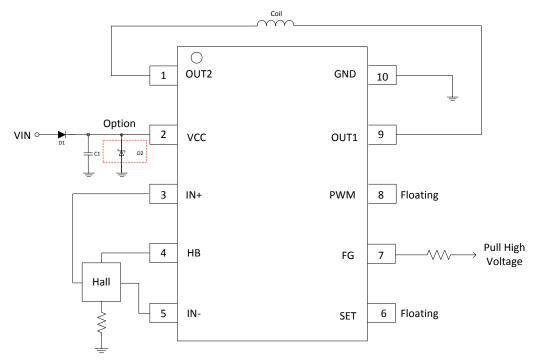


Figure 3. Typical Application 1

#### Type B: VCC speed control with slope setting

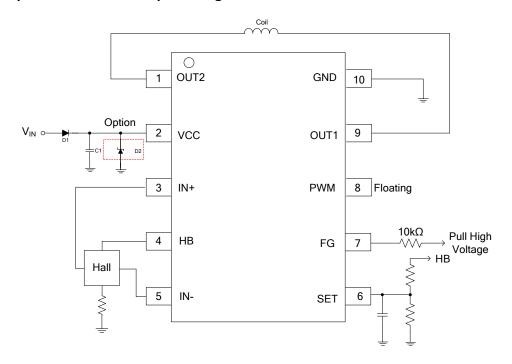


Figure 4. Typical Application 2

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#### Type C: Direct PWM input speed control

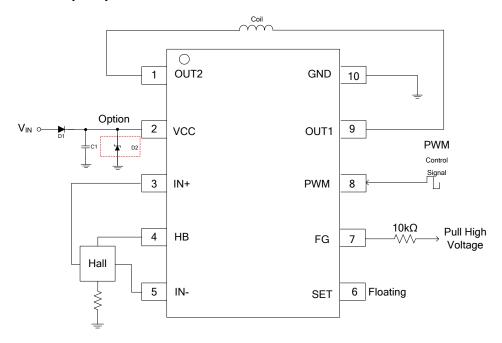


Figure 5. Typical Application 3

Note: for zener diode (D2) is optional choice.

#### **Function Description**

#### **Lockup Protection and Automatic Restart**

The SDC11558 provides the lockup protection and automatic restart functions for preventing the coil burn-out in the fan is locked. This IC has an internal counter to determine the shutdown time (t<sub>OFF</sub>) and restart time ( $t_{\text{ON}}$ ). During shutdown time, the output drivers keep turning off for 5 seconds and then enter the restart time. During the restart time, one output is high and the other is low, which makes a torque for fan rotation. The restart time has 0.5 second. If the locked condition is not removed, the shutdown restart process will be recurred until the locked condition is released (see Figure 6. Lockup/Auto Restart Waveform).



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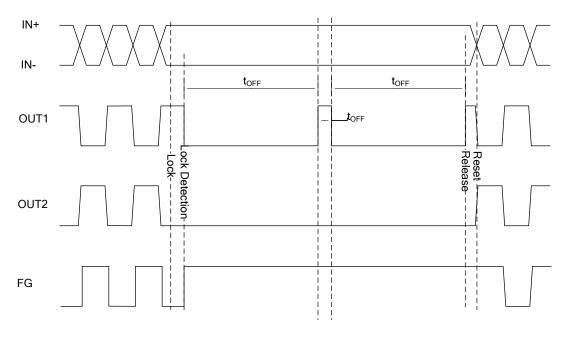


Figure 6. Lockup / Auto Restart Waveform

#### **Speed Control Function**

The SDC11558 builds in three speed control types, which

are VCC speed control (Type A), VCC speed control slope setting (Type B), and direct PWM input speed control (Type C).

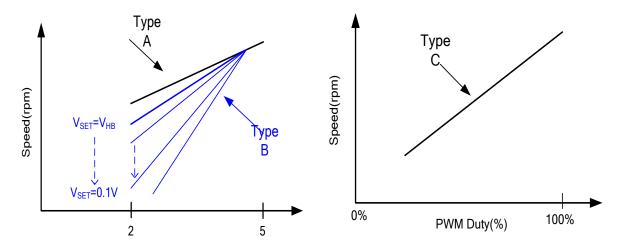


Figure 7. Speed Control Function

#### Quick Start and Standby Mode (Type C only)

This IC would enter standby mode when the PWM input keeps low level for more than 66.5ms (typ.). In standby mode, it will shutdown amplifier and FG. Thus, the supply current is around 100mA. In standby mode, the lock protection function doesn't work, therefore, starting fan is unobstructed when releasing standby mode.



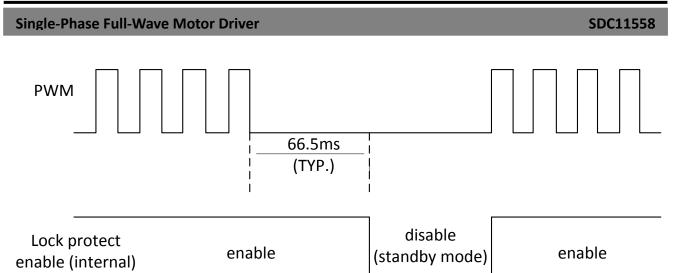


Figure 8. Quick Start Waveform

#### **Output Drivers**

All four drivers in the bridge output are designed for single phase full wave motor driver for fan motor. The linear output architecture is used as output driver.

#### **Low Duty Start up Function**

When motor start-up from stop condition, outputs are driven in not less than PWM 50% duty until detecting motor rotation(max 250 ms). Even if input duty of PWM is low, the motor can be started by this function. And if input duty of PWM is high, this function can limited the output current at starting moment, avoiding the impact of the power. When the IC is in lock protection mode, this function can also reduce the temperature rise.

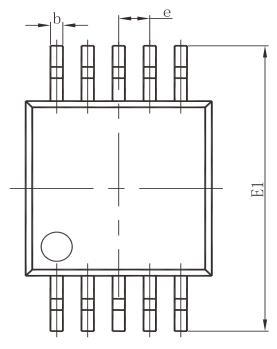
If V<sub>CC</sub> is greater than 4V, outputs are driven in PWM 50%

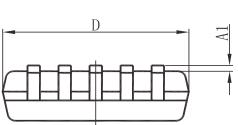
and 25 kHz Frequency when motor start-up or restart from lock protection mode.

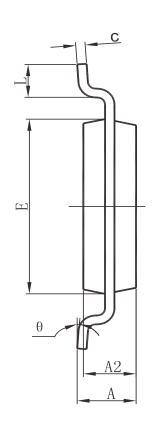
If  $V_{CC}$  is less than 4V, this function guarantees outputs keep continuous conduction 20 us at every rising edge of PWM signal, after whether conduction is determined by PWM signal: If FPWM is not less than 25 kHz and input duty of PWM is lower than 50%, the function will guarantee the starting duty greater than or equal to 50%;If input duty of PWM is higher than the guaranteed duty, then the starting duty will be equal to PWM signal duty; If FPWM is 50 kHz, the starting duty will be 100%; The opposite, if FPWM is less than 25 kHz and input duty of PWM is lower than 50%, the starting duty will be lower than 50%.

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# Package Dimension MSOP-10







Symbol	Dimensions I	n Millimeters	Dimensions In Inches		
	Min	Max	Min	Max	
А	0.820	1.100	0.032	0.043	
A1	0.020	0.150	0.001	0.006	
A2	0.750	0.950	0.030	0.037	
b	0.180	0.280	0.007	0.011	
С	0.090	0.230	0.004	0.009	
D	2.900	3.100	0.114	0.122	
е	0.50	(BSC)	0.020(BSC)		
E1	4.750	5.050	0.187	0.199	
E	2.900	3.100	0.114	0.122	
L	0.400	0.800	0.016	0.031	
θ	0°	6°	0°	6°	

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